Annex D: Calculation of momentum for relativistic non-elastic collision

During ideal non-elastic, i.e. plastic collision 2 masses hit each other in central position and are moving forward as a combined body without rotation. An approximation procedure is developed to calculate the end-velocity of this body on basis of the principle of conservation of momentum, in a case where the validity of equation $m_3 = m_1 + m_2$ is postulated. This approach is relevant for theoretical analysis only because it can be shown, that in real cases an additional increase of mass Δm_3 because the conversion of potential energy into mass must be considered. For details it is referred to chapter 7.1.

In addition, the appearing simple equation makes it possible to perform a comparison between the approximation procedures recursion, Newton's calculus, and bijection. The latter proved to be superior to the others because it is the only calculation to cover all possible input values and is therefore used also in other calculations in Annex A – C.

Respecting the above-mentioned restrictions, for the relativistic momentum using relation $m_3 = m_1 + m_2$ referring to Eq. (7.01)

$$p_0 = m_1 \gamma_1 v_1 + m_2 \gamma_2 v_2 = (m_1 + m_2) \gamma_3 v_3$$
 (D. 01)

applies, where v_3 can be calculated on basis of numerical approximation. In the following different procedures will be presented and the results are compared.

D.1 Recursion procedure

The procedure with the smallest mathematical effort is the procedure using simple recursion. The equation for the development can be derived directly using Eq. (D.01) and shows the form

$$\frac{(v_3)_{k+1}}{c} = \frac{p_0}{c(m_1 + m_2)\gamma_{3k}} = \frac{p_0}{c(m_1 + m_2)} \sqrt{1 - \left(\frac{(v_3)_k}{c}\right)^2}$$
 (D. 02)

D.2 Procedure according to Newton's calculus

Iteration according to Newton' calculus is generally using the sequence

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$
 (D.03)

When Eq. (D.01) is converted it applies first

$$\frac{m_1 \gamma_1 v_1 + m_2 \gamma_2 v_2}{m_1 + m_2} - \gamma_3 v_3 = 0 = f(v_3)$$
 (D. 04)

and then

$$f\left(\frac{v_3}{c}\right) = \frac{p_0}{c(m_1 + m_2)} - \frac{v_3}{c} \left(1 - \frac{{v_3}^2}{c^2}\right)^{-1/2}$$
 (D. 05)

Using

$$x = \frac{v_3}{c} \tag{D.06}$$

it yields

$$f(x) = \frac{p_0}{(m_1 + m_2)} - x(1 - x^2)^{-1/2}$$
 (D. 07)

and

$$f'(x) = -(1 - x^2)^{-3/2}$$
 (D. 08)

After inserting the result in Eq. (D.03) the iteration formula is finally

$$\frac{(v_3)_{k+1}}{c} = \frac{(v_3)_k}{c} + \frac{\frac{p_0}{(m_1 + m_2)} - (v_3)_k \left[1 - \left(\frac{(v_3)_k}{c}\right)^2\right]^{-1/2}}{c \left[1 - \left(\frac{(v_3)_k}{c}\right)^2\right]^{-3/2}}$$
(D. 09)

D.3 Bisection method

First the starting function is defined using Eq. (D.01)

$$f(v_3) = \gamma_3 v_3 = \frac{p_0}{(m_1 + m_2)}$$
 (D. 10)

where the value for p_0 is defined by the initial starting conditions. For the beginning of the calculation appropriate values for $(v_{3+})_0$ and $(v_{3-})_0$ are determined which are following the conditions

$$f(v_{3+})_0 > \frac{p_0}{(m_1 + m_2)}$$
 (D.11)

and

$$f(v_{3-})_0 < \frac{p_0}{(m_1 + m_2)} \tag{D.12}$$

In the interval $[(v_{3-})_0; (v_{3+})_0]$ the function $f(v_3)$ must be continuous and differentiable, and further $f'(v_3) \neq 0$ is required, which means, that in the chosen interval no minima and maxima are allowed, because otherwise no exact solution exists. Then the mean value is formed

$$(v_3)_1 = \frac{(v_{3+})_0 + (v_{3-})_0}{2}$$
 (D.13)

and $f(v_3)_1$ is calculated according to (D.10). The following equations apply:

$$f(v_3)_1 > \frac{p_0}{(m_1 + m_2)} : \Rightarrow (v_{3+})_1 = (v_3)_1 \text{ und } (v_{3-})_1 = (v_{3-})_0$$
 (D. 14)

$$f(v_3)_1 < \frac{p_0}{(m_1 + m_2)} : \Rightarrow (v_{3+})_1 = (v_{3+})_0 \text{ und } (v_{3-})_1 = (v_3)_1$$
 (D.15)

The calculation is repeated with increasing index 1 to n until the required accuracy is achieved. Every step of the calculation is generating a bisection of the difference between v_{3+} and v_{3-} . A standard calculation program (e.g. Microsoft Excel®) with the utilization of 15 digits is therefore requiring, because of the general estimation

$$2^{10} = 1024 \approx 10^3 \tag{D.16}$$

following

$$10^{15} \approx 2^{50} \tag{D.17}$$

the use of approximately 50 steps to reach maximum possible accuracy; in practice a utilization of 60 proved to be safe in any case. Because of the boundary condition $v_1 = 0$ the starting values can be determined easily and are $(v_{3-})_0 = 0$ resp. $(v_{3+})_0 = v_2$.

D.4 Evaluation

In the following results for the discussed procedures are presented using different values for the velocities. According to the considerations in chapter 7.1 only cases will be viewed, where the masses are equal and one of the selected velocities (here v_1) is equal to zero. All iteration methods lead to the same values; the procedures using simple recursion and according to Newton share the advantage, that they converge very quickly for small values of v/c. However, as a drawback the convergence is reducing for increasing v/c and starting with $p_0 = \gamma_2 v_2 \ge 2c$ (for $m_1 = m_2 = 1$) calculations are no longer possible. Bisection, however, shows a much better performance and is above approx. $v_2/c > 0.895$ the only remaining procedure which is still working.

In the following table examples for calculations with different conditions are presented. In all cases it is marked, from which iteration step on no differences between consecutive steps can be detected and so the procedure has reached its end (Status "x" in field "St"). If one of the procedures is not converging, then it is marked as "not ok" in the evaluation field. Further on the differences to the results of the relativistic addition of velocities $v_{3,Rel}$ are presented as percentage-value.

For the calculation, the following equations are used:

$$\frac{v_{3,Rel}}{c} = \frac{1 - \sqrt{1 - \left(\frac{v_2}{c}\right)^2}}{\frac{v_2}{c}} \qquad \qquad \gamma_{3,Rel} = \frac{1}{\sqrt{1 - \left(\frac{v_{3,Rel}}{c}\right)^2}} \qquad \qquad \frac{p_0}{c} = m_2 \gamma_2 \frac{v_2}{c}$$

$$\text{Recursion:} \qquad \frac{(v_3)_{k+1}}{c} = \frac{p_0}{c(m_1 + m_2)} \sqrt{1 - \left(\frac{(v_3)_k}{c}\right)^2}$$

Newton

$$\frac{(v_3)_{k+1}}{c} = \frac{(v_3)_k}{c} + \left\{ \frac{p_0}{c(m_1 + m_2)} - \frac{(v_3)_k}{c} \left[1 - \left(\frac{(v_3)_k}{c} \right)^2 \right]^{-1/2} \right\} \left[1 - \left(\frac{(v_3)_k}{c} \right)^2 \right]^{3/2}$$

Bisection:
$$\frac{(v_3)_{k+1}}{c} = \frac{(v_{3-})_k + (v_{3+})_k}{2c}$$

Condition
$$f(v_3)_{k+1} > \frac{p_0}{(m_1 + m_2)} : \Rightarrow (v_{3+})_{k+1} = (v_3)_{k+1} \text{ and } (v_{3-})_{k+1} = (v_{3-})_k$$

Condition
$$f(v_3)_{k+1} < \frac{p_0}{(m_1 + m_2)} : \Rightarrow (v_{3+})_{k+1} = (v_{3+})_k \text{ and } (v_{3-})_{k+1} = (v_3)_{k+1}$$

Appropriate starting values: For
$$\frac{(v_{3-})_0}{c} = -\frac{v_1}{c}$$
 and for $\frac{(v_{3+})_0}{c} = \frac{v_1}{c}$

Values in the fields for results (blue color): For Recursion, Newton and Bisection the last values of iteration.

$$\frac{v_3}{v_{3,Rel}}$$
 – 1 Comparison of results. Chosen was bisection (v_3) and relativistic addition of velocities ($v_{3,Rel}$)

For the presented calculations, the following values apply:

Tab. D.1	Tab D.2	Tab D.3
$m_1 = 1; m_2 = 1$	$m_1 = 1; m_2 = 1$	$m_1 = 1$: $m_2 = 1$
$v_1 = 0 \; ; \; v_2 = 0.1c$	$v_1 = 0$; $v_2 = 0.8c$	$v_1 = 0 \; ; \; v_2 = 0.89c$

Codes for calculation:

Coordinate		Code
G1	=	(1-SQRT(1-B2*B2))/B2
G2	=	1/SQRT(1-G1*G1)
B3	=	B2/SQRT(1-B2*B2)
B5	=	IF(B6="ok";B70;"")
D5	=	IF(D6="ok";D70;"")
F5	=	IF(F6="ok";F70;"")
H5	=	F5/G1-1
В6	=	IF(C70="";"not ok";"ok")
D6	=	IF(E70="";"not ok";"ok")
F6	=	IF(G70="";"not ok";"ok")
B8	=	B70/D70-1
D8	=	D70/F70-1
F8	=	F70/B70-1
G10	=	B1
H10	=	B2
B11	=	B\$3/(1+D\$2)*SQRT(1-B10*B10)
C11	=	IF(B11=B10);"x";"")
D11	=	D10+(B\$3/(1+D\$2)-D10*(1-D10*D10)^-(1/2))*((1-D10*D10)^(3/2))
E11	=	IF(D11=D10);"x";"")
F11	=	(G10+H10)/2
G11	=	IF(F11/SQRT(1-F11*F11) <b\$3 (1+d\$2);f11;g10)<="" td=""></b\$3>
H11	=	IF(F11/SQRT(1-F11*F11) <b\$3 (1+d\$2);h10;f11)<="" td=""></b\$3>
l11	=	IF(F11=F10;"x";"")

The codes B11 to I11 to be copied as far as B70 to I70

Annex D: Calculation of momentum for relativistic non-elastic collision

	A	В	С	D	Е	F	G	н	ı
	v ₁ /c =	0		$m_2/m_1 =$		v _{3,Rel} /c =	0,05012563		
	v2/c=	0,1		1		γ _{3,Rel} =	1,00125866		
	$p_0/c =$	0,1005037815				1.577.000			
	- 7	Recursion		Newton		Bisection			
	v3/c=	0,0501885613		0,0501885613		0,0501885613	$v_3/v_{3,Rel} =$	0,1%	
		nicht ok		ok		ok	The Control of		
1		Recursion/Newton		Newton/Bisection		Bisection/Recursion			
		0,0E+00		7,1E-15		-7,2E-15			
	k	v ₃ /c	St	v ₃ /c	St	$(v_{3-}+v_{3+})/2c$	v ₃₋ /c	v ₃₊ /c	S
5	0	0		0		103 310	0	0,1	
	1	0,0502518908		0,0502518908		0,0500000000	and the second second	0,1000000000	
,	2	0,0501884013		0,0501885616		0,0750000000		0,0750000000	
2	3	0,0501885617		0,0501885613		0,0625000000		0,0625000000	
	4	0,0501885613		0,0501885613	х	0,0562500000		0,0562500000	
	5	0,0501885613		0,0501885613	X	0,0531250000		0,0531250000	
	6	0,0501885613		0,0501885613	X	0,0515625000		0,0515625000	
5	7	0,0501885613	x	0,0501885613	×	0,0507812500		0,0507812500	
3	8	0,0501885613	×	0,0501885613	×	0,0503906250		0,0503906250	
	9	0,0501885613	X	0,0501885613		0,0501953125		0,0501953125	
0	10	0,0501885613		0,0501885613	X	0,0500976563		0,0501953125	
1	11	0,0501885613	X	0,0501885613	X	0,0501464844			
1			X		×			0,0501953125	
3	12	0,0501885613	X	0,0501885613	X	0,0501708984		0,0501953125	
1	13	0,0501885613	X	0,0501885613	Х	0,0501831055		0,0501953125	
	14	0,0501885613	х	0,0501885613	X	0,0501892090		0,0501892090	
1	15	0,0501885613	X	0,0501885613	×	0,0501861572		0,0501892090	
	16	0,0501885613	X	0,0501885613	х	0,0501876831		0,0501892090	
1	17	0,0501885613	Х	0,0501885613	х	0,0501884460		0,0501892090	
	18	0,0501885613	х	0,0501885613	X	0,0501888275		0,0501888275	
	19	0,0501885613	×	0,0501885613	×	0,0501886368		0,0501886368	
	20	0,0501885613	X	0,0501885613	×	0,0501885414		0,0501886368	
1	21	0,0501885613	Х	0,0501885613	Х	0,0501885891		0,0501885891	
2	22	0,0501885613	X	0,0501885613	X	0,0501885653		0,0501885653	
	23		X	0,0501885613	×	0,0501885533		0,0501885653	
	24	0,0501885613	X	0,0501885613	X	0,0501885593	Talacopalaroca policy designation	0,0501885653	
	25	0,0501885613	X	0,0501885613	Х	0,0501885623		0,0501885623	
3	26	0,0501885613	X	0,0501885613	×	0,0501885608		0,0501885623	
7	27	0,0501885613	х	0,0501885613	X	0,0501885615		0,0501885615	
3	28	0,0501885613	X	0,0501885613	X	0,0501885612		0,0501885615	
9	29	0,0501885613	X	0,0501885613	Х	0,0501885613	0,0501885612	0,0501885613	
	30	0,0501885613	X	0,0501885613	X	0,0501885612	0,0501885612	0,0501885613	
1	31	0,0501885613	х	0,0501885613	x	0,0501885613	0,0501885613	0,0501885613	
2	32	0,0501885613	X	0,0501885613	x	0,0501885613	0,0501885613	0,0501885613	
0	50	0,0501885613	х	0,0501885613	х	0,0501885613	0.0501885613	0,0501885613	
1	51	0,0501885613	X	0,0501885613	X	0,0501885613		0,0501885613	
2	52	0,0501885613	X	0,0501885613	X	0,0501885613		0,0501885613	
3	53		×	0,0501885613	X	0,0501885613		0,0501885613	
4	54	0,0501885613	X	0,0501885613		0,0501885613		0,0501885613	
4					X				
5	55	0,0501885613	X	0,0501885613	X	0,0501885613	0,0501885613	0,050188561	3

Tab. D.1: Velocity v_3 after relativistic non-elastic collision, $v_1=0$; $v_2=0$,1c

Annex D: Calculation of momentum for relativistic non-elastic collision

	A	В	C	D	Ε	F	G	Н	J
ij	v ₁ /c =	0		m ₂ /m ₁ =		v _{3,Rel} /c =	0,50000000		
2	v2/c=	0,8		1		$\gamma_{3,Rel}$ =	1,15470054		
1	$p_0/c =$	1,3333333333				1.570000			
9		Recursion		Newton		Bisection			
	v3/c=	0,5547001962		0,5547001962		0,5547001962	v ₃ /v _{3,Rel} =	10,9%	
1		ok		ok		ok	7 (35)		
7		Recursion/Newton		Newton/Bisection		Bisection/Recursion			
ij		0,0E+00		4,7E-15		-4,6E-15			
	k	v ₃ /c	St	v ₃ /c	St	$(v_{3-}+v_{3+})/2c$	v ₃₋ /c	v ₃₊ /c	S
o	0	0	100	0	103	(-33+11	0	0,8	
	1	0,6666666667		0,6666666667		0,4000000000		0,8000000000	
2	2	0,4969039950		0,5723540713		0,6000000000		0,6000000000	
<u>۔</u> 3	3	0,5785370130		0,5550845393		0,5000000000		0,6000000000	
4	4	0,5437707542		0,5547003739		0,5500000000		0,6000000000	
id T	5	0,5594891983		0,5547003739		0,5750000000		0,5750000000	
5				0,5547001962					
	6 7	0,5525584281		0,5547001962	1441	0,5625000000		0,5625000000	
4		0,5556494433		FOR THE CASE OF THE STREET AND A STREET	×	0,5562500000			
	8	0,5542777868		0,5547001962	×	0,5531250000		0,5562500000	
7 8 9	9	0,5548878305		0,5547001962	Х	0,5546875000		0,5562500000	
일	10	0,5546167828		0,5547001962	X	0,5554687500		0,5554687500	
1 2 3	11	0,5547372648		0,5547001962	×	0,5550781250		0,5550781250	
4	12	0,5546837205		0,5547001962	X	0,5548828125		0,5548828125	
1	13	0,5547075186		0,5547001962	Х	0,5547851563		0,5547851563	
	14	0,5546969418		0,5547001962	X	0,5547363281		0,5547363281	
	15	0,5547016426		0,5547001962	X	0,5547119141		0,5547119141	
1	16	0,5546995534		0,5547001962	X	0,5546997070		0,5547119141	
7	17	0,5547004819		0,5547001962	Х	0,5547058105		0,5547058105	
3	18	0,5547000692		0,5547001962	X	0,5547027588		0,5547027588	
1	19	0,5547002527		0,5547001962	×	0,5547012329		0,5547012329	
9	20	0,5547001711		0,5547001962	X	0,5547004700	0,5546997070	0,5547004700	1
3	21	0,5547002074		0,5547001962	Х	0,5547000885	0,5547000885	0,5547004700)
1	22	0,5547001913		0,5547001962	Х	0,5547002792	0,5547000885	0,5547002792	
1	23	0,5547001984		0,5547001962	×	0,5547001839	0,5547001839	0,5547002792	
3	24	0,5547001952		0,5547001962	x	0,5547002316	0,5547001839	0,5547002316	
3	25	0,5547001967		0,5547001962	х	0,5547002077	0,5547001839	0,5547002077	
3	26	0,5547001960		0,5547001962	x	0,5547001958	0,5547001958	0,5547002077	1
7	27	0,5547001963		0,5547001962	x	0,5547002017	0,5547001958	0,5547002017	
1	28	0,5547001962		0,5547001962	x	0,5547001988	0,5547001958	0,5547001988	
1	29	0,5547001962		0,5547001962	×	0,5547001973	0,5547001958	0,5547001973	
9	30	0,5547001962		0,5547001962	x	0,5547001965	0,5547001958	0,5547001965	
1	31	0,5547001962		0,5547001962	×	0,5547001962		0,5547001965	
j	32	0,5547001962		0,5547001962	x	0,5547001963		0,5547001963	
								WATER AND THE RESERVE OF THE SECOND	
0	50	0,5547001962	X	0,5547001962	X	0,5547001962		0,5547001962	
1	51	0,5547001962	X	0,5547001962	X	0,5547001962		0,5547001962	
4	52	0,5547001962	X	0,5547001962	x	0,5547001962		0,5547001962	
2 3 4	53	0,5547001962	X	0,5547001962	×	0,5547001962		0,5547001962	
4	54	0,5547001962	X	0,5547001962	Х	0,5547001962		0,5547001962	
5	55	0,5547001962	Х	0,5547001962	X	0,5547001962	0,5547001962	0,5547001962	3

Tab. D.2: Velocity v_3 after relativistic non-elastic collision, $v_1=0$; $v_2=0.8c$

Annex D: Calculation of momentum for relativistic non-elastic collision

	A	В	C	D	Ε	F	G	H	
	v1/c=	0		$m_2/m_1 =$		v _{3.Rel} /c =	0,61128031		
	v2/c=	0,89		1		$\gamma_{3,Rel}$ =	1,26356090		
	$p_0/c =$	1,9519233617				1.578.000			
		Recursion		Newton		Bisection			
	v3/c=			0,6984528781		0,6984528781	v ₃ /v _{3,Rel} =	14,3%	
i		not ok		ok		ok			
į		Recursion/Newton		Newton/Bisection		Bisection/Recursion			
Ī		3,4E-02		0,0E+00		-3,3E-02			
i	k	v ₃ /c	St	v ₃ /c	St	$(v_{3-}+v_{3+})/2c$	v ₃₋ /c	v ₃₊ /c	
	0	0	100	0	-	(13-13-11-1	0	0,89	110
	1	0,9759616809		0,9759616809		0,4450000000	0,4450000000		
2	2	0,2127032246		0,9397078220		0,6675000000	0,6675000000	A TANK OF THE PARTY OF THE PART	
1	3	0,9536286032		0,8688424449		0,7787500000	0,6675000000		
j	4	0,2937506647		0,7743135001		0,7231250000		0,7231250000	
į	10.00								
	5	0,9329042795		0,7115556340		0,6953125000	0,6953125000		
1	6	0,3514676442		0,6988106129		0,7092187500	0,6953125000		
	7	0,9136953543		0,6984531401		0,7022656250	0,6953125000		
4	8	0,3966306344		0,6984528781		0,6987890625	0,6953125000		
ļ	9	0,8959116343		0,6984528781		0,6970507813	0,6970507813		
1	10	0,4335537100		0,6984528781	X	0,6979199219	0,6979199219		
ļ	11	0,8794661312		0,6984528781	×	0,6983544922	0,6983544922		
1	12	0,4645201595		0,6984528781	X	0,6985717773	0,6983544922		
	13	0,8642751101		0,6984528781	Х	0,6984631348	0,6983544922		
	14	0,4909276759		0,6984528781	X	0,6984088135	0,6984088135		
-	15	0,8502581396		0,6984528781	X	0,6984359741	0,6984359741		
l	16	0,5137129813		0,6984528781	X	0,6984495544	0,6984495544		
1	17	0,8373381377		0,6984528781	Х	0,6984563446	0,6984495544	13.5	
1	18	0,5335439275		0,6984528781	Х	0,6984529495	0,6984495544	0,6984529495	
1	19	0,8254414098		0,6984528781	X	0,6984512520	0,6984512520	0,6984529495	
	20	0,5509184645		0,6984528781	X	0,6984521008	0,6984521008	0,6984529495	
Į	21	0,8144976752		0,6984528781	х	0,6984525251	0,6984525251	0,6984529495	,
Į	22	0,5662205832		0,6984528781	х	0,6984527373	0,6984527373	0,6984529495	,
Į	23	0,8044400793		0,6984528781	×	0,6984528434	0,6984528434	0,6984529495	,
3	24	0,5797542286		0,6984528781	x	0,6984528965	0,6984528434	0,6984528965	,
1	25	0,7952051896		0,6984528781	х	0,6984528700	0,6984528700	0,6984528965	,
1	26	0,5917650167		0,6984528781	x	0,6984528832	0,6984528700	0,6984528832	
7	27	0,7867329748		0,6984528781	x	0,6984528766	0,6984528766	0,6984528832	
j	28	0,6024547712		0,6984528781	x	0,6984528799	0,6984528766	0,6984528799	,
1	29	0,7789667662		0,6984528781	х	0,6984528782	0,6984528766		
	30	0,6119916160		0,6984528781	x	0,6984528774	0,6984528774	100	
į	31	0,7718532028		0,6984528781	x	0,6984528778	0,6984528778		
	32	0,6205171991		0,6984528781	x	0,6984528780	0,6984528780		
	50	0,6671025921		0,6984528781	Х	0,6984528781	0,6984528781	11.7	
]	51	0,7270581323		0,6984528781	×	0,6984528781	0,6984528781		
2	52	0,6700717735		0,6984528781	×	0,6984528781	0,6984528781		
4	53	0,7244527587		0,6984528781	X	0,6984528781	0,6984528781		
1	54	0,6727542511		0,6984528781	х	0,6984528781	0,6984528781		
3	55	0,7220808780		0,6984528781	X	0,6984528781	0,6984528781	0,6984528781	

Tab. D.3: Velocity v_3 after relativistic non-elastic collision, $v_1=0$; $v_2=0.89c$